

Regenerative Power Module And Common Bus RPM Panels

Instruction Manual



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PRODUCT MANUAL SAFETY INFORMATION

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The recommendations in this manual do not take precedence over any of the following requirements relating to cranes, hoists lifting devices or other material handling equipment which use or include Magnetek Products:

- Instructions, manuals, and safety warnings of the manufacturers of the equipment where the radio system is used,
- Plant safety rules and procedures of the employers and the owners of facilities where the Magnetek Products are being used,
- Regulations issued by the Occupational Health and Safety Administration (OSHA),
- Applicable local, state or federal codes, ordinances, standards and requirements, or
- Safety standards and practices for the industries in which Magnetek Products are used.

This manual does not include or address the specific instructions and safety warnings of these manufacturers or any of the other requirements listed above. It is the responsibility of the owners, users and operators of the Magnetek Products to know, understand and follow all of these requirements. It is the responsibility of the employer to make its employees aware of all of the above listed requirements and to make certain that all operators are properly trained. No one should use Magnetek Products prior to becoming familiar with and being trained in these requirements and the instructions and safety recommendations in this manual.

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Disclaimer of Warranty

Magnetek, hereafter referred to as Company, assumes no responsibility for improper programming of a drive by untrained personnel. A drive should only be programmed by a trained technician who has read and understands the contents of this manual. Improper programming of a drive can lead to unexpected, undesirable, or unsafe operation or performance of the drive. This may result in damage to equipment or personal injury. Company shall not be liable for economic loss, property damage, or other consequential damages or physical injury sustained by the purchaser or by any third party as a result of such programming. Company neither assumes nor authorizes any other person to assume for Company any other liability in connection with the sale or use of this product.



Improper settings of this product can lead to unexpected, undesirable, or unsafe operation or performance of the controls.

General Description

The Regenerative Power Module (RPM) is a universal brake chopper circuit designed to dissipate regenerative energy produced by a motor into a fixed resistor load. The universal module covers the DC supply voltage range from 200V to 660V. The voltage selector link located on the outside front cover of the unit configures the module for LOW voltage (200V to 300V), MED voltage (300V to 500V) or HIGH voltage (500V to 660V).

The module is powered from the DC bus and requires no additional power supplies. The module can either be connected behind the M contactor of each drive or can be connected to the incoming DC bus using a separate mounted controller that includes additional protective components and line capacitance.

This module is required whenever the main power supply cannot receive the regenerated power being return to the line. The voltage on the OmniPulse DDC bus rises rapidly during regeneration (100 ms). Bus feed rectifier units that do not have a dump circuit or have slow reacting circuits require the use of the RPM module and dump resistor.

RPM Features

Ratings

Minimum 200VDC
Maximum 660 VDC
Minimum 256 VDC
Maximum 800 VDC
400A
800A
10% (40° C ambient)
5% (60° C ambient)
1 ohm
60° C
-20° C

Universal Module (Voltage selector link, located on the front of the unit, configures module to DC Bus voltage)

Link Setting	DC Bus Range
330 V (Low)	200 – 300 VDC
495 V (Medium)	300 – 500 VDC
660 V (High)	500 – 660 VDC

Voltage Display

A 10-LED Switch Level bar graph provides a visual display of the approximate bus voltage level when the brake transistor turns on.

Simplified Switching Level Selection

An 8-position DIP switch provides transistor turn on switching level selection in 15 steps.

Link Setting	Adj Range	Volt/Step
330	256 – 400 VDC	16
495	384 - 600	24
660	512 - 800	32

Choose the appropriate setting for the voltage link set up and set the appropriate corresponding DIP switch position on. All other DIP settings must be off.

• Mode Switches

A 4-position DIP switch provides the following configuration selections:

DIP Position	Off Setting On Setting	
1	Enable Ext Intlk	Disable Ext Intlk
2	Auto Reset	Remote Reset
3	2-Term Res 3-Term Res	
4	Not Used	Not Used

The External Interlock may be used for the connection of a normally closed temperature switch mounted at the power resistor.

• Overheat Protection

The thermistor mounted on the heat sink is used to protect against failure caused by excessive duty combined with excessive ambient temperatures. The unit is shut down when the heat sink temperature exceeds 95° C.

• 24V Output for Fan

A +24V Fan output is available for supplemental cooling. The Fan output is capable of delivering up to 5W for the addition of an external fan separately mounted from the RPM unit. The output becomes active when the heat sink temperature exceeds 65° C.

• LED Fault and Status Indicators

LED status indicators provide the following indications:

COLOR	MARKING	DESCRIPTION
GREEN	POWER	Indicates that the brake chopper power supply is
		present
GREEN	INTERLOCK	Indicates that the external contact is closed when the
		interlock is enabled or that the interlock is in the
		disabled position
GREEN	READY	Indicates that no fault condition exists and that the
		external interlock is not open
AMBER	ACTIVE	Indicates that the brake chopper is conducting
AMBER	RESET	Indicates that the reset circuit is activated
RED	OVERTEMP	Indicates that the heat sink temperature has reached
		95° C and the module has shut down to protect the
		transistor.
RED	IGBT FAULT	Indicates that the module is shut down on short
		circuit IGBT detection

• TEST Switch

The TEST switch simulates a DC bus voltage increase; this input is used to set the turn on voltage and verify transistor and resistor functionality.

External Control Terminals

A pluggable Phoenix screw terminal connector is provided to facilitate additional functionality:

Pin	Signal Name	Function		
1	External	Allows control circuit of the brake module to be powered from		
	+24V Supply	an external supply.		
		(Eliminates 25ms delay for control power to become		
		established from main DC bus power.)		
2	Fault	24 volts between this terminal and terminal 9 or 10 indicates		
		that the brake module is in a fault condition. This can be used		
		for remote fault annunciation.		
3	Sync	Connect to same terminal of other brake modules to		
		synchronize switching in order to balance brake load between		
		two or more modules.		
		The 0V pins of synchronized modules must also be connected		
		together.		
4	Reset	Apply positive pulse between 10V and 24V to remotely reset a		
		brake module fault.		
5	Fan	The 24-volt DC Fan output is capable of delivering up to 5W of		
		power for the addition of an external fan separately mounted		
		from the RPM unit. The output becomes active when the heat		
		sink temperature exceeds 65° C. Connect between terminals 5		
(D 1	and 10.		
7	Ready	24 Volt output, RPM ready		
/	Level	Brake level switching allows the switching voltage turn on		
		level to be reduced by as much as 100 volts. The voltage input to terminal 7 can be fixed or variable and needs to be connected		
		to the 0V circuit common. See FIGURE 1 for a graphic representation of the dynamic adjustment capability.		
8	I-Lock	Connection point for resistor overheat protection switch.		
O	1-LUCK	Normally-closed switch: Connect between either terminals 8		
		and 9 or 8 and 10. Input has a 50 ms filter to reduce noise.		
9	0V	Control circuit common.		
10	0V	Control circuit common		
10	U ¥	Condoi circuit common		

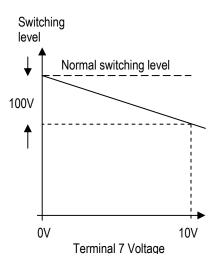


FIGURE 1
Turn On Dynamic Adjustment

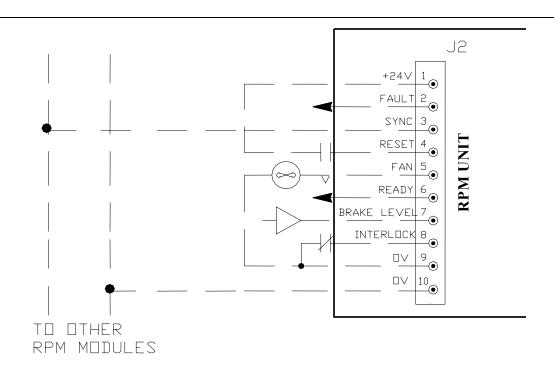


FIGURE 2
Syncrhonization Connection

Power Terminal Connections

TERM	Function		
L1+	DC Bus Positive		
L2-	DC Bus Negative		
R1+	Resistor Positive		
	(Same potential as DC Bus Positive)		
R2-	Resistor Negative		
	(Switched Output)		
R3+	Terminal must be connected to the external resistor whenever the		
	separate mounted RPM panel with the required additional		
	protective components is connected directly to the DC bus. See		
	FIGURE 4 for example connections.		

External Power Connection

An external 24V supply may be connected to the brake chopper at pins 1 and 10. The internal 24 and 15 volt power supplies of the brake chopper is derived from the main DC bus input and takes approximately 50ms to start up. If it is necessary for the brake chopper to be active within less than 50ms of applying the DC bus voltage an external power supply should be provided.

The external 24-volt DC supply is not needed on crane applications using the OmniPulse DDC.

Synchronization

Synchronization equalizes the power dissipation in the braking resistors.

When two or more brake chopper modules are connected to the same DC bus they should be synchronized by linking together all of the SYNC signals on all modules and linking together a 0V common from each module. See FIGURE 2 for connection.

When the DC bus voltage exceeds the voltage threshold of any of the brake choppers the SYNC signal will turn all of them on. The DC bus voltage must fall below the voltage threshold of all choppers in order for the synchronized modules to turn off.

Resistor Sizing

The minimum connected resistor to the standard RPM module is 1 ohm. The resistor value can be greater than this but never lower. Use the following procedure to calculate the continuous current rating of the resistor chosen.

- 1. Tabulate all motion Full Load Amps (FLA)
 - ½ hour FLA for hoist motion
 - 1 hour FLA for travel motions
- 2. Calculate Regen Current for simultaneous motion operation

$$I_{REGEN} = \left(\sum_{FLA} *0.8\right) + \left(\sum_{TRAVEL} *0.3\right)$$

3. Size RPM Unit(s) and external resistors as close as possible to calculated value.

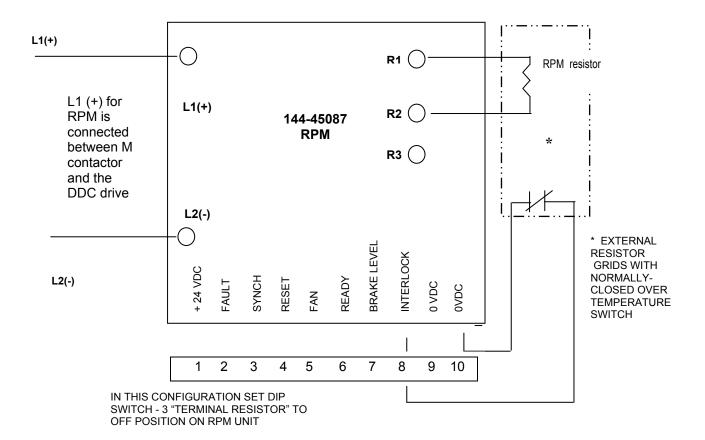


FIGURE 3
400 AMP Single RPM Unit

The connection shown in FIGURE 3 is a single 400 AMP RPM Unit that is connected to the DDC bus after the M contactor. This is the simplest connection possible and requires no additional protective components.

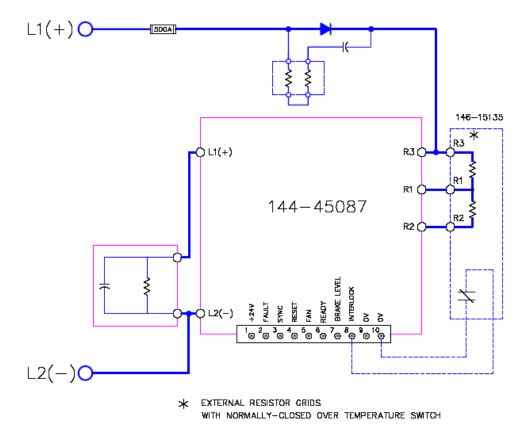


FIGURE 4
400 AMP 230-320V Common Bus RPM Panel

The connection in FIGURE 4 shows a separately mounted 400 AMP RPM Panel that is connected across the 230-320V. The panel is generally connected on the load side of the Manual Magnetic Disconnect Switch. Connections direct to the DC Bus require additional protective components that are included on the separately mounted RPM panel.



Warning: Connecting the RPM Module directly to the DC Bus without the additional components shown above can result in damage to the RPM unit and other equipment on the common bus.

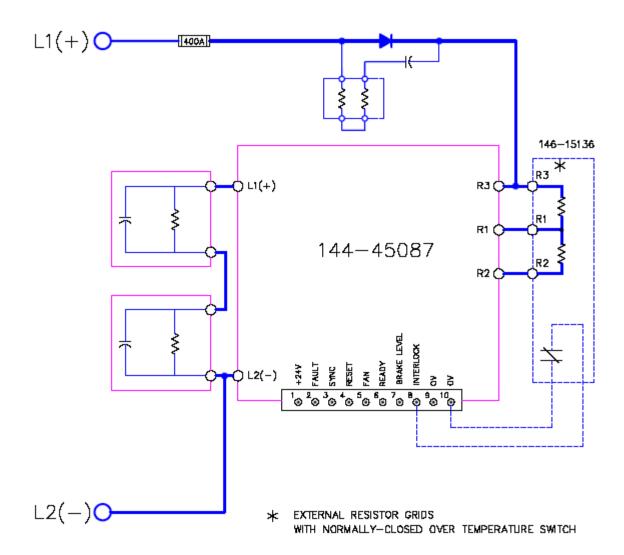


FIGURE 5
400 AMP 360-720V Separate Mounted

The connection in FIGURE 5 shows a separately mounted 400 AMP RPM Panel that is connected across the 360-720V. The panel is generally connected on the load side of the Manual Magnetic Disconnect Switch. Connections direct to the DC Bus require additional protective components that are included on the separately mounted RPM panel.

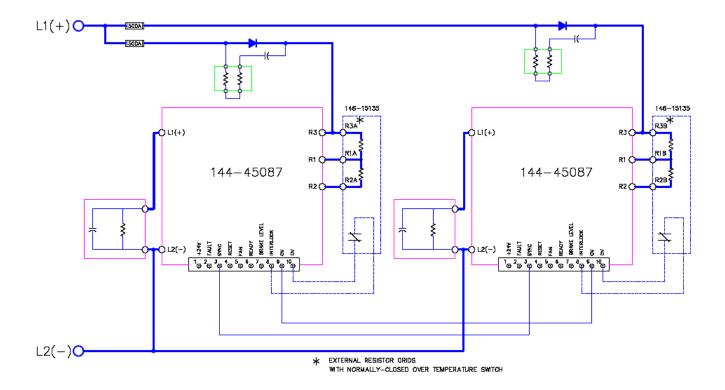


FIGURE 6
800 AMP 230-320V Separate Mounted RPM Panel

The connection in FIGURE 6 shows an 800 AMP RPM Panel that is connected across the 230-320V. The panel is generally connected on the load side of the Manual Magnetic Disconnect Switch. The Synchronization line is connected between both RPMs in order to have proper load sharing.

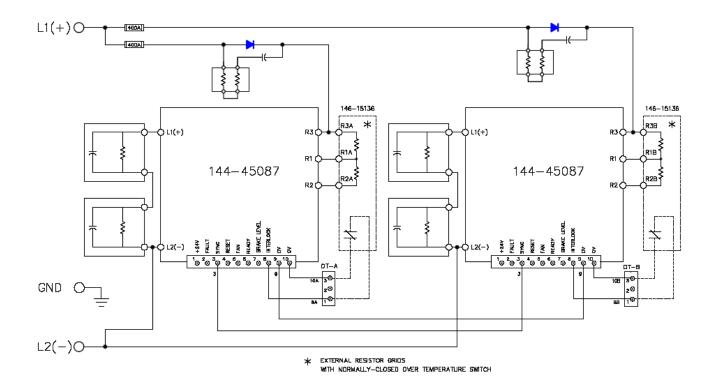


FIGURE 7
800 AMP 360-720V Separate Mounted RPM Panel

The connection in FIGURE 7 shows an 800 AMP RPM Panel that is connected across the 360-720V. The panel is generally connected on the load side of the Manual Magnetic Disconnect Switch. The Synchronization line is connected between both RPMs in order to have proper load sharing.

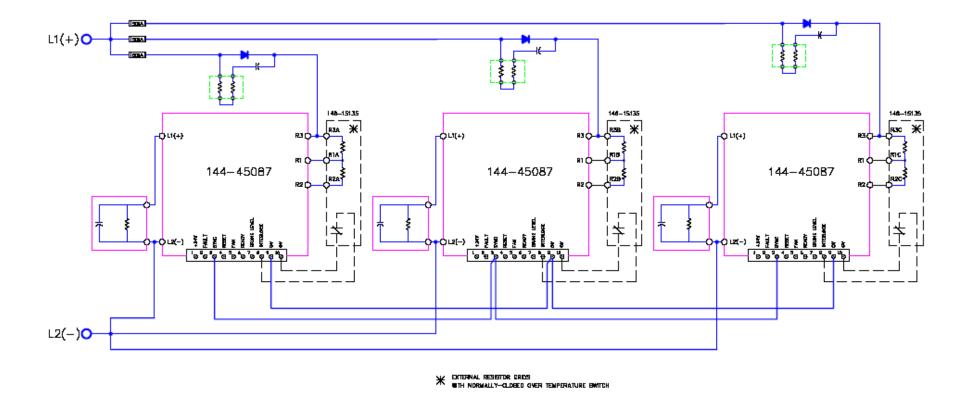


FIGURE 8 1200 AMP 230-360V Common Bus RPM Panel

The connection in FIGURE 8 shows a 1200 AMP RPM Panel that is connected across the 230-360V. The panel is generally connected on the load side of the Manual Magnetic Disconnect Switch. The Synchronization line is connected between both RPMs in order to have proper load sharing.

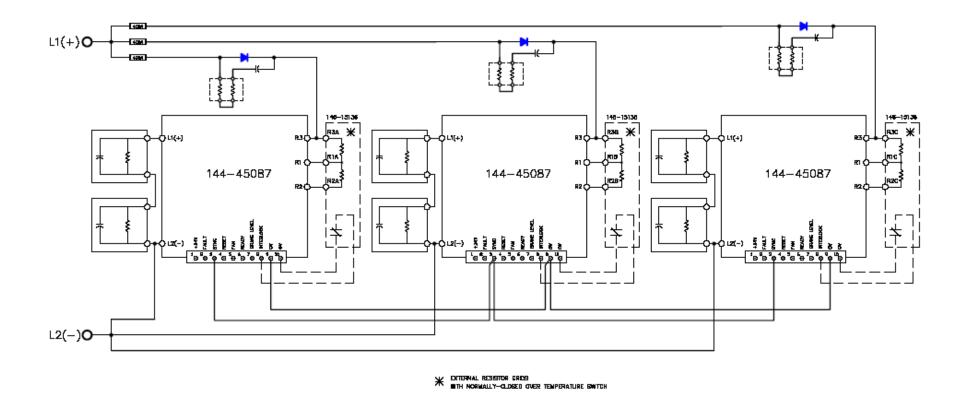


FIGURE 9
1200 AMP 360-720V Common Bus RPM Panel

The connection in FIGURE 9 shows a 1200 AMP RPM Panel that is connected across the 360-720V. The panel is generally connected on the load side of the Manual Magnetic Disconnect Switch. The Synchronization line is connected between both RPMs in order to have proper load sharing.

Troubleshooting

Taking the following measurements can check the transistor and diode.

Q1	POSITIVE PROBE	NEGATIVE PROBE	READING
DP	R2	L1	0.312
DN	L2	R2	0.312
QP	L1	R2	> 0.6
QN	R2	L2	> 0.6

TRANSISTOR AND DIODE CHECK USING D.M.M. SET ON DIODE SCALE

FIGURE 10

If the Green POWER indicator light on the front cover is out make the following checks.

- 1. Check for the supply voltage between L1+ and L2-
- 2. If the supply voltage is present replace the entire RPM unit.

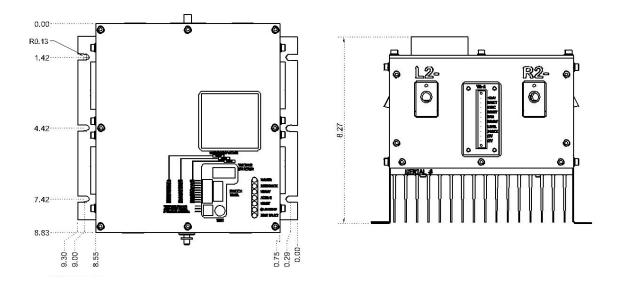


FIGURE 11
Dimensions 400 AMP RPM Unit

Enclosure Dimensions

The following table describes the dimensions for the common bus RPM panels. The NEMA 4 enclosures have screw latches to secure the hinged door.

Part Number	Description	Dimensions (in)		(in)
		Height	Width	Length
144-45111	400 Amp/230~320 VDC RPM Panel	30	24	16
144-45112	800 Amp/230-320 VDC RPM Panel	48	36	16
144-45113	1200 Amp/230~320 VDC RPM Panel	48	36	16
144-45114	400 Amp/360~720 VDC RPM Panel	30	24	16
144-45115	800 Amp/360~720 VDC RPM Panel	48	36	16
144-45116	1200 Amp/360~720 VDC RPM Panel	48	36	16

FIGURE 12
Enclosure Dimensions for the Common Bus RPM Panels